

Lecture 6/13: Generative Models so far

train $P(x)$ = density / curve [param] fit to data x (Sep for each x)

predict $P(x|Y) = \frac{P(x|Y) \cdot P(Y)}{P(x)}$

• For each Y $P(x|Y) = N(x|\mu, \Sigma)$ ^{D-dim} $\Rightarrow$ Gauss DA

• For each Y $P(x|Y) = P(x^1 x^2 \dots x^D | Y)$
 $= P(x^1|Y) \cdot P(x^2|Y) \dots P(x^D|Y) \Rightarrow$ Naive Bayes

• Not-So-Naive: $\rightarrow$ ^{Belief Network} group features that are very dependent

For each Y : $P(x|Y) = P(x^1 x^2 \dots x^D | Y) =$

$= P(\boxed{x^1, x^2} | Y) \cdot P(\boxed{x^3} | Y) \cdot P(\boxed{x^4, x^5} | Y, x^1) \cdot P(x^6, x^7 | Y)$

^{2dim} ^{1-dim} ^{2dim fit for x^1}

^{indep}

MIXT OF GAUSSIANS (GMM)

Today +

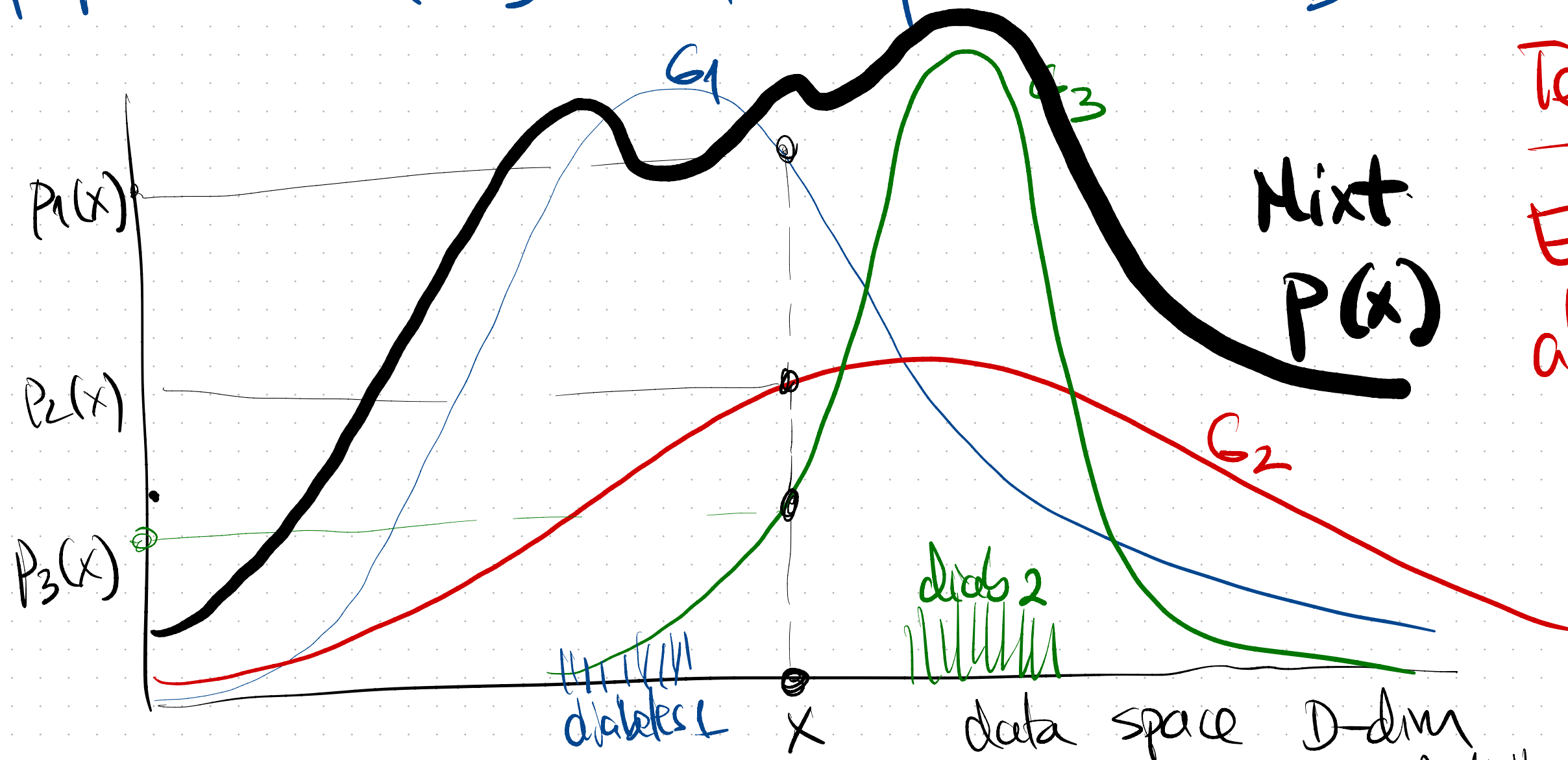
Next

$$P(x) = \underbrace{w_1}_{\text{fixed}} \underbrace{N_1(x | \mu_1, \Sigma_1)}_{D=\text{dim}} + \underbrace{w_2}_{\text{fixed}} \underbrace{N_2(x | \mu_2, \Sigma_2)}_{D=\text{dim}} + \underbrace{w_3}_{\text{fixed}} \underbrace{N_3(x | \mu_3, \Sigma_3)}_{D=\text{dim}}$$

$w_1 + w_2 + w_3 = 1$
proportions

$K=3$ # of "components"

$D = \# \text{ data dim}$



Technique

$E(xp)$ $M(ax)$
algorithm

Mixture adv: ability to fit data with multiple "bells"
"Groups"

Recap for intuition: Kmeans clustering algorithm.

X is data $\Rightarrow$ cluster into $K=6$ groups
 $i=1:N$ $k=1:6$

• π_{ik} = membership
 $\begin{cases} 1 & \text{if } x_i \rightarrow \text{cluster } k \\ 0 & \text{if not} \end{cases}$

E-step
calculate π_{ik} , given μ_k

M-Step
calculate μ_k , given π_{ik}

• μ_k = centroid for cluster k
param

$$\pi_{ik} = 1 \text{ for closest } \mu_k \\ = \arg \min_k \|x_i - \mu_k\|^2$$

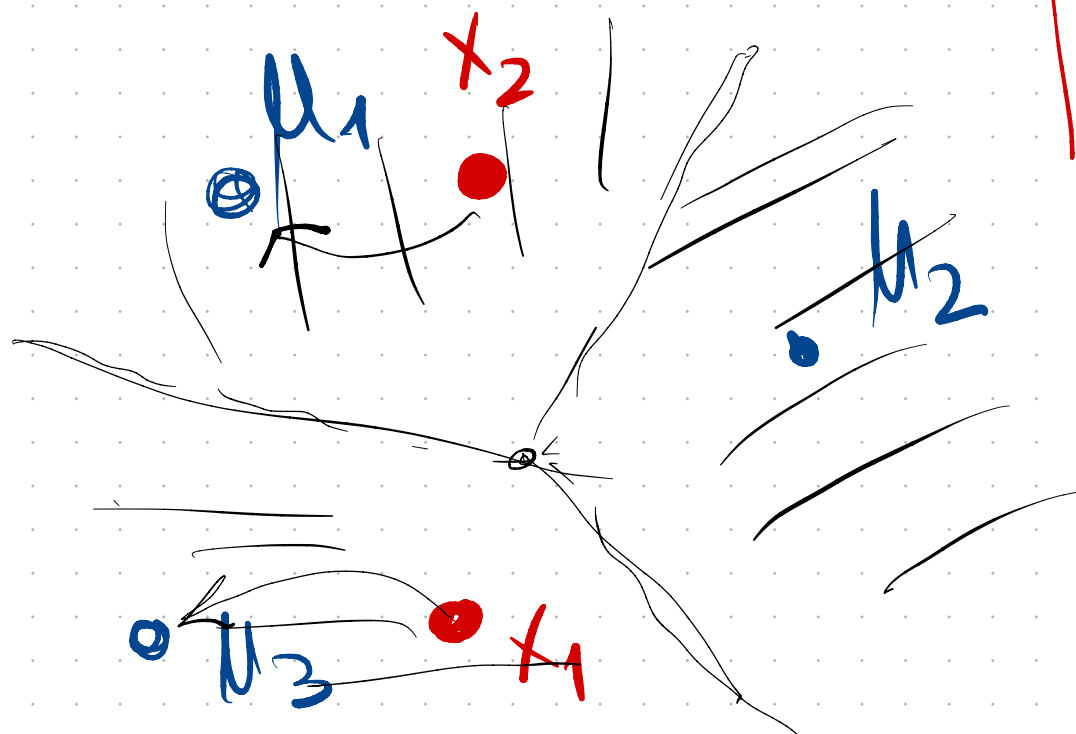
$$\mu_k = \text{avg of } (x \text{ points}) \\ \text{in cluster } k$$

$$= \frac{\sum_{i=1}^N x_i \cdot \pi_{ik}}{\sum_{i=1}^N \pi_{ik}}$$

filter only points in cluster k

$$\sum_{i=1}^N \pi_{ik} = N_k = \# \text{ of points in cluster } k$$

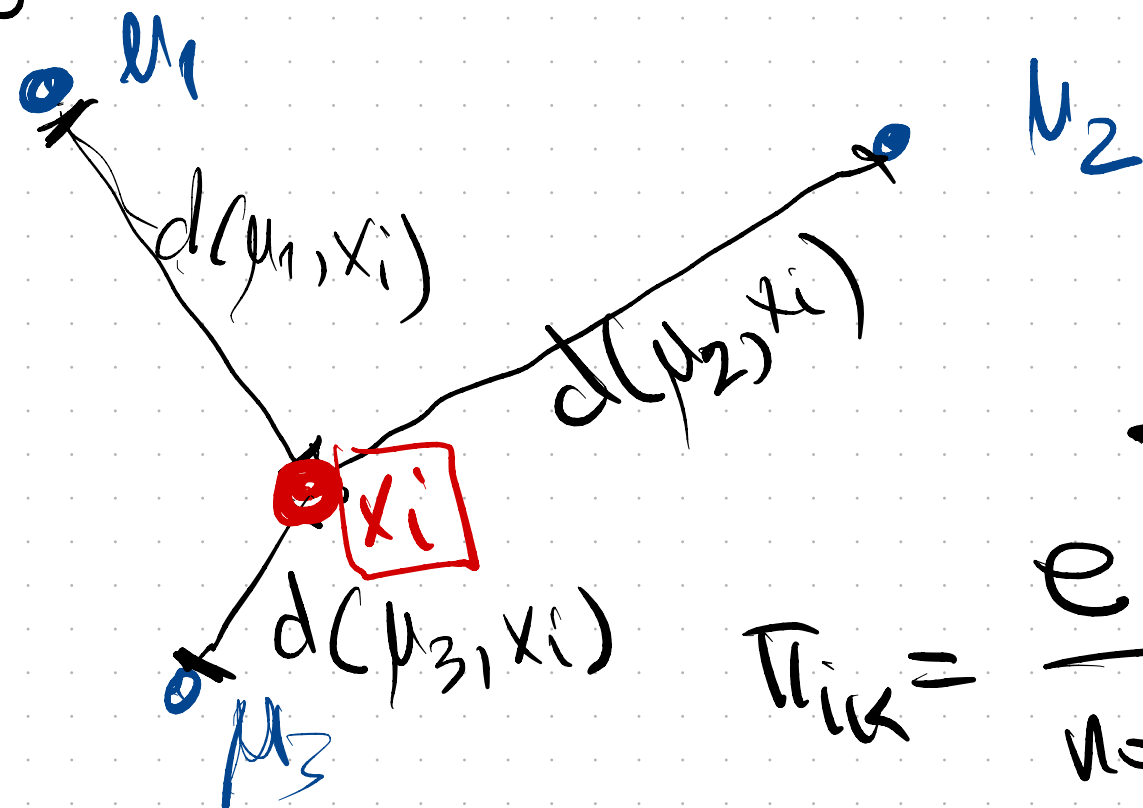
HARD: π_{ik}



Soft: $\pi_{ik} = \text{prob}(x_i \rightarrow \mu_k)$

E step

- score dist $\Rightarrow$ probability
reg output



$$\mu_k =$$

M step (same)

$$\mu_k = \frac{\sum_{i=1}^n x_i \cdot \pi_{ik}}{\sum_{i=1}^n \pi_{ik}}$$

proportion
(weight)

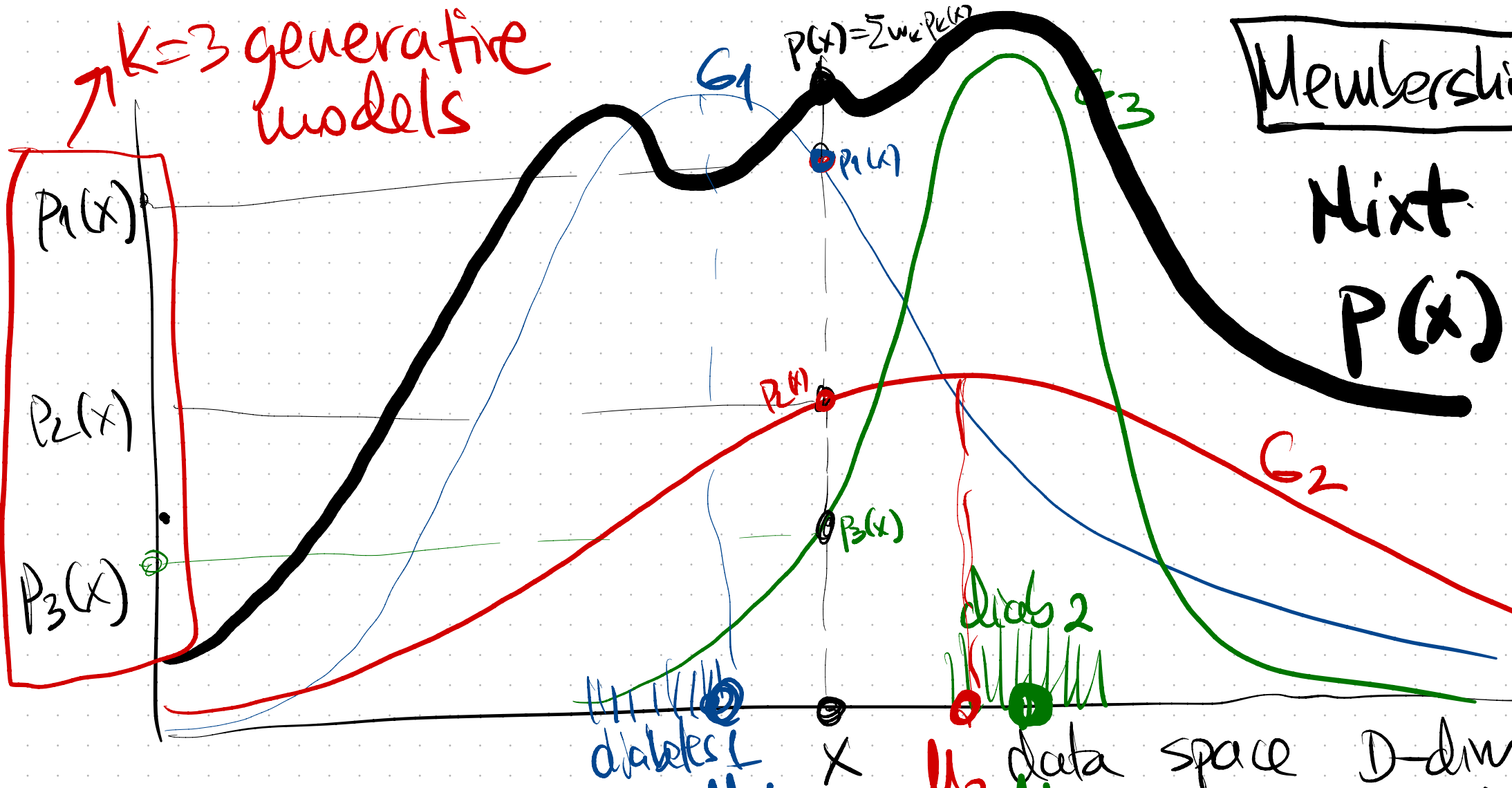
$\rightarrow$ weighted avg
 $N_k = E[\# \text{ points}]$
in cluster k

$$\pi_{ik} = \frac{e^{-\frac{1}{2} \|x_i - \mu_k\|^2}}{\text{normalized over all } k}$$

fix datapoint x_i small dist $\|x_i - \mu_k\|^2 \equiv$ large π_{ik}

$[\pi_{i1} \pi_{i2} \dots \pi_{ik}]$ distribution over clusters

- parts of x_i distributed $\rightarrow x_i \cdot \pi_{ik}$
- which cluster/group x_i is in $\Rightarrow$ which generator μ_k produced datap x_i



Membership π_{ik} = prob that x_i was generated by Gauss k

Mixt $P(x) = \frac{\text{pr}(k \text{ gen}(x_i))}{w_k \cdot \text{pr}(x_i | \mu_k, \Sigma_k)}$

Normalized over all k

CONST: w_k = size of cluster/source k

$E[\# \text{datap}]$ from k

$= \sum_{i=1}^N \pi_{ik}$

Mixture adv: ability to fit data with multiple "hills" μ_{clusters}

$P(x) = \sum_{k=1}^3 w_k \cdot \left(N_k(x | \mu_k, \Sigma_k) \right)$

$D\text{-dim}$

prob to observe patient/email/car x_i overall sources $k=1, k=2, \dots, k=K$

π_{ik} = probab of source/generator k for observed datap x_i (model the evidence)
 w_k = prob of source/gen k in general (prior) $\rightarrow$ given x_i

E step

calculate π_{ik} given
 params $(\mu_k, \Sigma_k, w_k)_{k=1:K}$

$$\pi_{ik} = \text{pr}(k \text{ source generated } x_i) \\ = \text{pr}(k | x_i) = \frac{\text{pr}(x_i | k) \cdot \text{pr}(k)}{\text{pr}(x_i)}$$

$$= \frac{N_k(x_i | \mu_k, \Sigma_k) \cdot w_k}{\text{normalize over } k \text{ generators}}$$

normalize over k
 generators

M step

calculate param $(\mu_k, \Sigma_k, w_k)_{k=1:K}$
 given
 memberships π_{ik}

• Loglikelihood (data) = $LL(x)$

• take expectation w.r.t π_{ik}
 $E[LL(x)] \approx LL(x)$

• take differentials Constrain $w_1 + w_2 + w_3 = 1$

$$\left. \begin{array}{l} \frac{\partial LL(x)}{\partial \mu_k} = 0 \\ \frac{\partial LL(x)}{\partial \Sigma_k^{-1}} = 0 \end{array} \right| \text{Lagrangean} \left. \frac{\partial LL(x)}{\partial w_k} = ? \right|$$