

# LOGISTIC REGRESSION

CS6140

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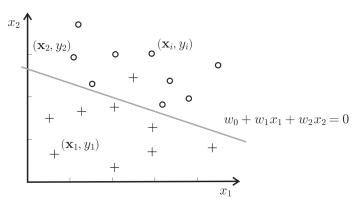
Fall 2024

### LINEAR CLASSIFICATION

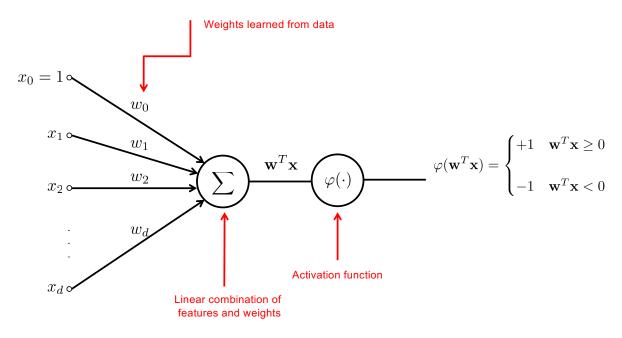
**Given:** a set of observations  $\mathcal{D} = \{(\boldsymbol{x}_i, y_i)\}_{i=1}^n, (\boldsymbol{x}_i, y_i) \in \mathbb{R}^d \times \{0, 1\}$ 

**Objective:** find best linear separator  $f(\mathbf{x}) = 0$ , where  $f(\mathbf{x}) = w_0 + \sum_{j=1}^d w_j x_j$ 

$$\mathcal{X} = \mathbb{R} \times \mathbb{R}, \, \mathcal{Y} = \{0, 1\}$$

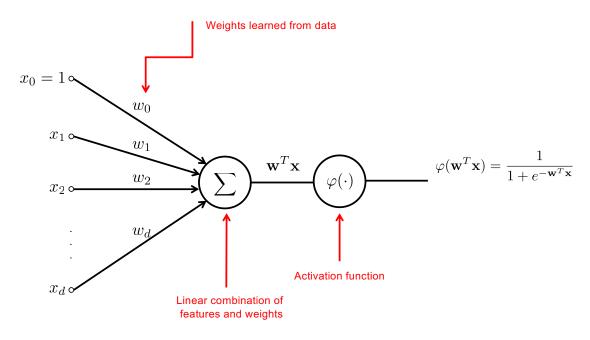


### **Perceptron**



Input Output

### LOGISTIC REGRESSION



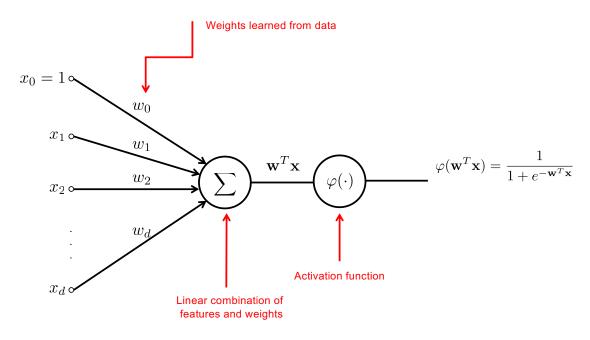
Input Output

# **ACTIVATION FUNCTIONS**

$$\varphi(t) = \frac{1}{1+e^{-t}} \qquad \leftarrow \text{ sigmoid function}$$

$$\varphi(t) = \frac{1}{2} \cdot \left(1 + \frac{t}{\sqrt{1+t^2}}\right)$$

### LOGISTIC REGRESSION



Input Output

### THINKING ABOUT LOGISTIC REGRESSION

Can we model the (X,Y) dependence using a linear combination?

$$\mathcal{X} = \{1\} \times \mathbb{R}^d, \, \mathcal{Y} = \{0, 1\}$$

$$P(Y = 1|\mathbf{x}) = \mathbf{w}^T \mathbf{x}$$

How about the odds function?

$$\underbrace{\frac{P(Y=1|\mathbf{x})}{1-P(Y=1|\mathbf{x})}}_{\text{odds function}} = \mathbf{w}^T \mathbf{x}$$

How about the log odds function?

$$\log \frac{P(Y=1|\mathbf{x})}{1 - P(Y=1|\mathbf{x})} = \mathbf{w}^T \mathbf{x}$$

### MAXIMIZING LIKELIHOOD

$$P(Y=1|\mathbf{x},\mathbf{w}) = \frac{1}{1+e^{-\mathbf{w}^T\mathbf{x}}}$$

$$\mathcal{X} = \{1\} \times \mathbb{R}^d, \, \mathcal{Y} = \{0, 1\}$$

Let's express the probability mass function as:

$$p(y|\mathbf{x}, \mathbf{w}) = \begin{cases} \left(\frac{1}{1 + e^{-\mathbf{w}^T \mathbf{x}}}\right)^y & \text{for } y = 1\\ \left(1 - \frac{1}{1 + e^{-\mathbf{w}^T \mathbf{x}}}\right)^{1 - y} & \text{for } y = 0 \end{cases}$$

And make it more compact:

$$p(y|\mathbf{x}, \mathbf{w}) = \left(\frac{1}{1 + e^{-\mathbf{w}^T \mathbf{x}}}\right)^y \left(1 - \frac{1}{1 + e^{-\mathbf{w}^T \mathbf{x}}}\right)^{1-y}$$

### MAXIMIZING LIKELIHOOD

Given: a set of observations 
$$\mathcal{D} = \{(\boldsymbol{x}_i, y_i)\}_{i=1}^n, \ (\boldsymbol{x}_i, y_i) \in \mathcal{X} \times \mathcal{Y}$$
  $\mathcal{X} = \{1\} \times \mathbb{R}^d, \ \mathcal{Y} = \{0, 1\}$ 

Let's express the conditional likelihood as:

$$l(\mathbf{w}) = \prod_{i=1}^{n} p(y_i | \mathbf{x}_i, \mathbf{w}) \qquad \longrightarrow \qquad \mathbf{w}^* = \arg\max_{\mathbf{w}} \left\{ \prod_{i=1}^{n} p(y_i | \mathbf{x}_i, \mathbf{w}) \right\}$$

### UPDATE RULES TO MAXIMIZE LIKELIHOOD

$$\mathbf{w}^{(0)} = \text{something}$$
  
 $\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} + \Delta \mathbf{w}^{(t)}$ 

#### Maximum Likelihood:

$$\mathbf{w}^{(0)} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} + \eta \left( \mathbf{X}^T \mathbf{P}^{(t)} \left( \mathbf{I} - \mathbf{P}^{(t)} \right) \mathbf{X} \right)^{-1} \mathbf{X}^T \left( \mathbf{y} - \mathbf{p}^{(t)} \right)$$

$$\mathbf{p} = (p_1, p_2, \dots, p_n) \qquad \mathbf{P} = \operatorname{diag} \{\mathbf{p}\} \qquad p_i = P(Y_i = 1 | \mathbf{x}_i, \mathbf{w}) = \frac{1}{1 + e^{-\mathbf{w}^T \mathbf{x}_i}}$$
$$\mathbf{y} = (y_1, y_2, \dots, y_n) \qquad \mathbf{I} = \operatorname{identity matrix}$$

# MINIMIZING SUM OF SQUARED ERRORS

Given: a set of observations 
$$\mathcal{D} = \{(\boldsymbol{x}_i, y_i)\}_{i=1}^n$$
,  $(\boldsymbol{x}_i, y_i) \in \mathcal{X} \times \mathcal{Y}$   $\mathcal{X} = \{1\} \times \mathbb{R}^d$ ,  $\mathcal{Y} = \{0, 1\}$ 

Let's express the sum of squared errors as:

$$E(\mathbf{w}) = \sum_{i=1}^{n} (y_i - p_i)^2 = \sum_{i=1}^{n} e_i^2$$
  $p_i = P(Y_i = 1 | \mathbf{x}_i, \mathbf{w}) = \frac{1}{1 + e^{-\mathbf{w}^T \mathbf{x}_i}}$ 

# UPDATE RULES TO MINIMIZE SUM OF SQUARED ERRORS

$$\mathbf{w}^{(0)} = \text{something}$$
  
 $\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} + \Delta \mathbf{w}^{(t)}$ 

#### Minimum Sum of Squared Errors:

$$\mathbf{w}^{(0)} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} + \eta \left( \mathbf{J}^{(t)T} \mathbf{J}^{(t)} + \mathbf{J}^{(t)T} \mathbf{E}^{(t)} (2\mathbf{P}^{(t)} - \mathbf{I}) \mathbf{X} \right)^{-1} \mathbf{X}^T \mathbf{P}^{(t)} \left( \mathbf{I} - \mathbf{P}^{(t)} \right) \left( \mathbf{y} - \mathbf{p}^{(t)} \right)$$

$$\mathbf{p} = (p_1, p_2, \dots, p_n) \qquad \mathbf{P} = \operatorname{diag} \{\mathbf{p}\} \qquad \mathbf{e} = (y_1 - p_1, y_2 - p_2, \dots, y_n - p_n)$$

$$\mathbf{y} = (y_1, y_2, \dots, y_n) \qquad \mathbf{J} = \mathbf{P}(\mathbf{I} - \mathbf{P})\mathbf{X} \qquad \mathbf{E} = \operatorname{diag} \{\mathbf{e}\}$$

I = identity matrix

# UPDATE RULES, BATCH MODE

$$\mathbf{w}^{(0)} = \text{something}$$
  
 $\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} + \Delta \mathbf{w}^{(t)}$ 

#### Maximum Likelihood:

$$\mathbf{w}^{(0)} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} + \eta \left( \mathbf{X}^T \mathbf{P}^{(t)} \left( \mathbf{I} - \mathbf{P}^{(t)} \right) \mathbf{X} \right)^{-1} \mathbf{X}^T \left( \mathbf{y} - \mathbf{p}^{(t)} \right)$$

### Minimum Sum of Squared Errors:

$$\mathbf{w}^{(0)} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} + \eta \left( \mathbf{J}^{(t)T} \mathbf{J}^{(t)} + \mathbf{J}^{(t)T} \mathbf{E}^{(t)} (2\mathbf{P}^{(t)} - \mathbf{I}) \mathbf{X} \right)^{-1} \mathbf{X}^T \mathbf{P}^{(t)} \left( \mathbf{I} - \mathbf{P}^{(t)} \right) \left( \mathbf{y} - \mathbf{p}^{(t)} \right)$$

$$\mathbf{p} = (p_1, p_2, \dots, p_n) \qquad \mathbf{P} = \operatorname{diag} \{\mathbf{p}\} \qquad \mathbf{e} = (y_1 - p_1, y_2 - p_2, \dots, y_n - p_n)$$

$$\mathbf{y} = (y_1, y_2, \dots, y_n) \qquad \mathbf{J} = \mathbf{P}(\mathbf{I} - \mathbf{P})\mathbf{X} \qquad \mathbf{E} = \operatorname{diag} \{\mathbf{e}\}$$

 $\mathbf{I} = \mathrm{identity} \ \mathrm{matrix}$ 

# UPDATE RULES, BATCH MODE

$$\mathbf{w} \leftarrow \text{something}$$
  
 $\mathbf{w} \leftarrow \mathbf{w} + \Delta \mathbf{w}$ 

#### **Gradient Descent:**

$$\Delta \mathbf{w} = \eta \mathbf{X}^T \mathbf{P} \left( \mathbf{I} - \mathbf{P} \right) \left( \mathbf{y} - \mathbf{p} \right)$$

$$\Delta \mathbf{w} = \eta \cdot \begin{bmatrix} p_1(1-p_1) \\ p_1(1-p_1) \\ \vdots \\ p_1(1-p_1) \\ x_{1d} \end{bmatrix} x_{11} \begin{bmatrix} p_2(1-p_2)x_{21} & \cdots & p_n(1-p_n)x_{n1} \\ p_2(1-p_2)x_{22} & & & \\ \vdots \\ p_n(1-p_n)x_{nd} \end{bmatrix} \cdot \begin{bmatrix} e_1 \\ e_2 \\ \vdots \\ e_n \end{bmatrix}$$

$$\mathbf{x}_1$$

$$\Delta \mathbf{w} = \eta \sum_{i=1}^n e_i p_i (1-p_i) \mathbf{x}_i,$$

# UPDATE RULES, STOCHASTIC MODE

$$\mathbf{w} \leftarrow \text{something}$$

$$\mathbf{w} \leftarrow \mathbf{w} + \Delta \mathbf{w}$$

#### Gradient Descent:

$$\Delta \mathbf{w} = \eta \sum_{i=1}^{n} e_i p_i (1 - p_i) \mathbf{x}_i$$

#### Stochastic Gradient Descent:

$$\Delta \mathbf{w} = \eta e_i p_i (1 - p_i) \mathbf{x}_i$$

### **PREDICTION**

Given: a predictor defined by  $\mathbf{w}$  and a new data point  $\mathbf{x}$ 

$$P(Y = 1|\mathbf{x}, \mathbf{w}) = \frac{1}{1 + e^{-\mathbf{w}^T \mathbf{x}}}$$

$$r = \frac{w_0 + \sum_{j=1}^d w_j x_j}{\sqrt{\sum_{j=1}^d w_j^2}} \qquad \longleftarrow$$

distance from  $\mathbf{x}$  to hyperplane

$$P(Y = 1|\mathbf{x}) = \frac{1}{1 + e^{-r \cdot \sqrt{\sum_{j=1}^{d} w_j^2}}}$$