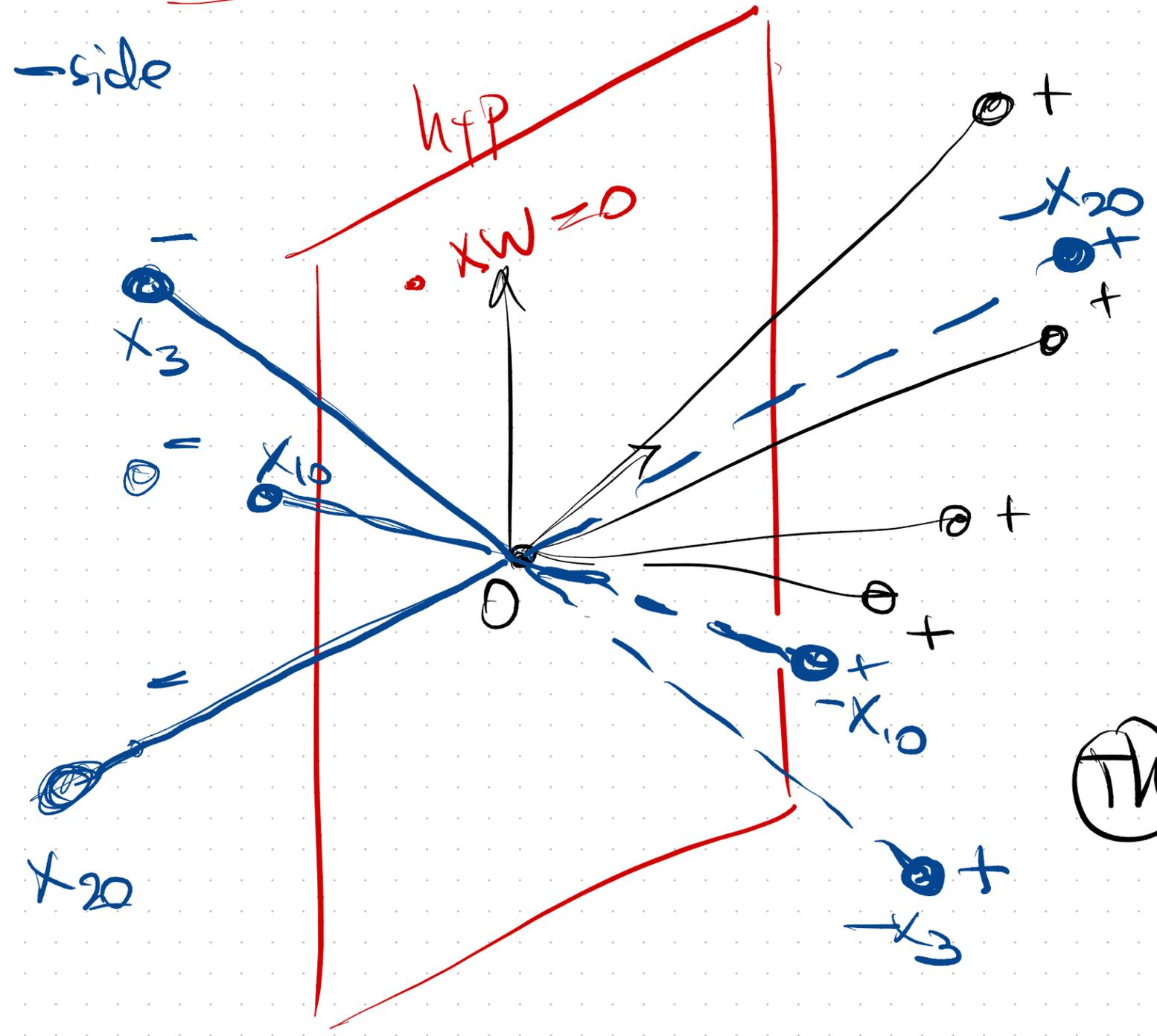


5/28: Perceptron: A linear model (simple) $h(x_i) = x_i w$ label \rightarrow +
 $y_i \leftarrow$ -
 $w = \text{coef.}$

New objective (geom) we want hyperplane $[xw=0]$ to separate $+/-$ side



Step 1 (before training): convert neg datapoints ($y=-$) into positive
 examples: $\begin{cases} x_i = -x_i \\ y_i = -y_i \end{cases}$ for negatives
 \Rightarrow All points pos $y_i = +$
 new OBJ: have all points on positive side

(11) Hyperplane 100% sep original data \iff Hyperplane new has 100% data on \oplus side.

Perceptron problem (modified data)

- Given N vectors x_1, x_2, \dots, x_N

- Find hyperplane w s.t. $x_i w \geq 0 \forall i$
(puts all points on pos side)

error $J(w) = \sum_{x_i} -x_i w \geq 0$

mistake
 $x_i w < 0$

pos
how far from
hyperplane x_i is

not mistake
(correct) $x_i w \geq 0$

OBS: no error \Rightarrow no mistakes

$\Rightarrow J(w) = 0$

$x_i w < 0$

update: Every mistake x_i gets added to $w = \text{normal of hyperplane}$

Gradient Descent update

$$\frac{\partial J}{\partial w^d} = - \frac{\partial x_i w}{\partial w^d} = - \frac{\partial [\sum_d x_i^d w^d]}{\partial w^d} = -x_i^d$$

if $x_i =$
 $= \text{mistake}$

$$\frac{\partial J}{\partial w} = -x_i^T$$

Vector

GD update for datapoint x_i

$$w_{\text{new}} = w_{\text{old}} + \lambda \cdot x_i^T$$

(all datapoints $x_i = \text{mistakes}$)

$$w_{\text{new}} = w_{\text{old}} + \lambda \sum_{x_i \text{ mistakes}} x_i^T$$

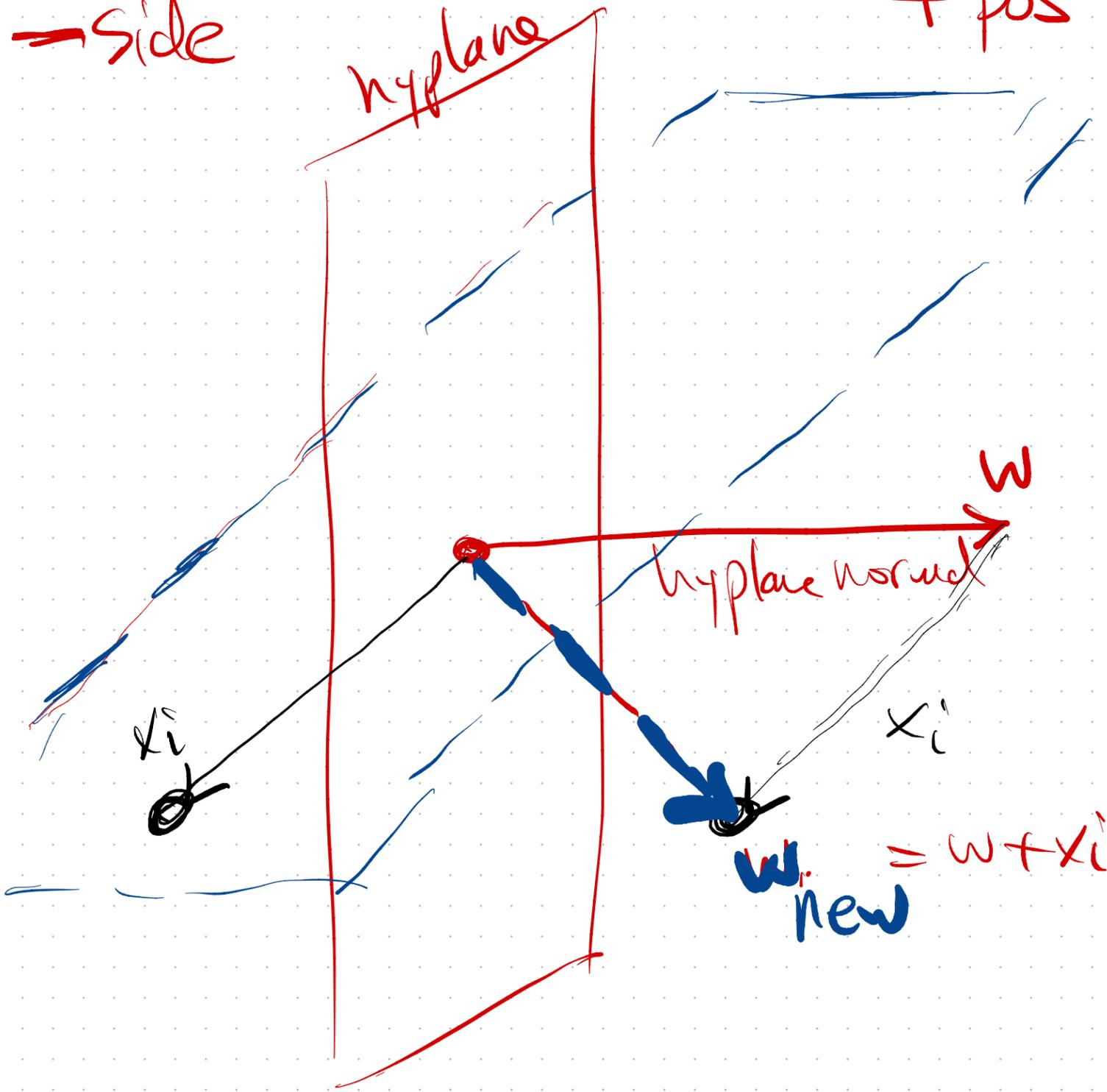
$\{x_i w < 0\}$

GD. upd. Geometrically

→ side

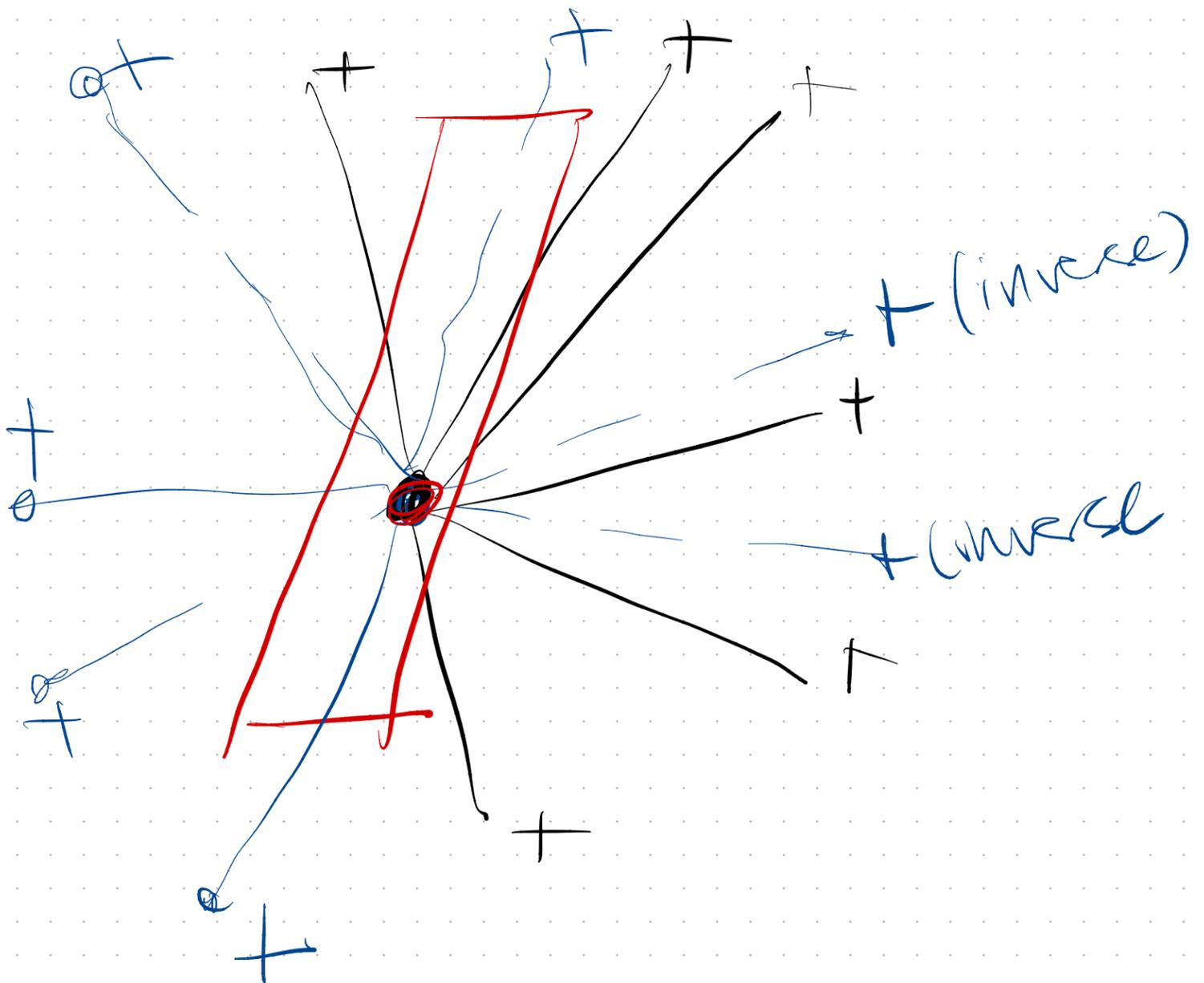
hyperplane

+ pos



$x_i = \text{mistake } (x_i w < 0)$
add x_i to w ($w_{new} = w + x_i$)

Geom: hyperplane rotated
TOWARDS x_i



\textcircled{Th} $x_1, x_2, x_3, \dots, x_N$ are linearly separable
 \Rightarrow (after step t) all points can be on $\textcircled{+}$ side of hyperplane \vec{w}
 \downarrow
0% error separates

Then Perceptron Alg will find a separator (0 mistakes) after finite # iterations

Proof: $w_k =$ hyperplane after k iterations.

update: one mistake at a time
 $x_k =$ datapoint (mistake) that updated w_k

$\alpha =$ scalar/const to be decided later

$$w_{k+1} = w_k + x_k^T \quad (\lambda = 1 \text{ simple})$$

$$w_{k+1} - \alpha \vec{w} = w_k - \alpha \vec{w} + x_k^T$$

\vec{w} is separator

$$x_k w_k < 0$$

$$\|w_{k+1} - \alpha \bar{w}\|^2 = \|w_k - \alpha \bar{w} + x_k^T\|^2 = \|w_k - \alpha \bar{w}\|^2 + 2x_k(w_k - \alpha \bar{w}) + \|x_k\|^2$$

$$= \|w_k - \alpha \bar{w}\|^2 + 2x_k w_k - 2x_k \alpha \bar{w} + \|x_k\|^2$$

x_k mistake for w_k

$$\leq \|w_k - \alpha \bar{w}\|^2 - 2x_k \alpha \bar{w} + \|x_k\|^2$$

choose $\alpha > 0$ large enough such that

strict pos $> \epsilon$ fixed
use $x_k \bar{w} > 0$
 \bar{w} hyp all points pos side

$$\leq \|w_k - \alpha \bar{w}\|^2 - \epsilon$$

$$\|w_{k+1} - \alpha \bar{w}\|^2 \leq \|w_k - \alpha \bar{w}\|^2 - \epsilon \Rightarrow \text{this cannot go on forever!}$$

- has to stop: no x_k mistake \Rightarrow 0% error
- \bar{w} does not exist: there is no hyperplane separator