

Data points (vectors)

	f_1	f_2	f_d
x_1			
x_2			
x_3			
\vdots			
x_N			

new representation on t features

A: $t \ll d$

$N \times d$

$N \times t$

each new feature g_i is a linear comb. of the original features.

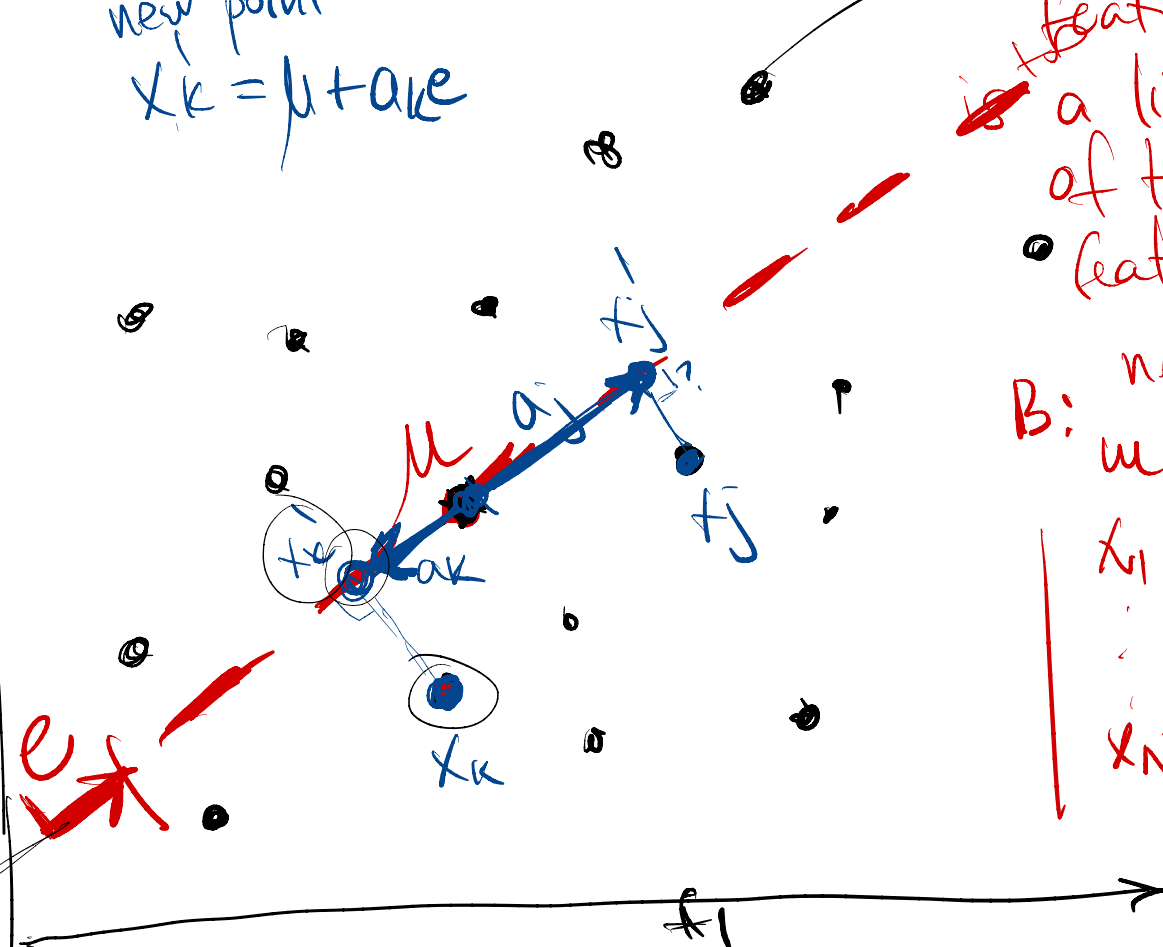
B: new data matrix

	t feat
x_1	
\vdots	
x_N	

$N \times t$
Orig

$d=2$
visualization

new point
 $x_k = \mu + a_k e$



(1) $t=0$ NO FEAT
represent whole X on 1 point

$\mu = \text{mean}(x)$
 $= E[x]$

$|e|=1$ direction of line

$t=1 \Rightarrow 1$ ^{new} dim \Rightarrow new representation will be on 1 line

guess: that "one line" new rep

- passes through μ .

- usually correspond to longest-direction stretch of data.

geom line: e, a_1, a_2, \dots, a_N
new coordinates

SSE / sq loss

error $J(a_1, a_2, \dots, a_N, e) = \sum_{k=1}^N \left\| \mu + a_k e - x_k \right\|^2 = \sum_k \|a_k e - (x_k - \mu)\|^2$

new point

orig point

$x_k = \mu + a_k e$

$x_k - \mu = a_k e$

$(x_k - \mu) e = a_k e^T x_k$

$= \sum_k a_k^2 \|e\|^2 - 2 \sum_k a_k e^T (x_k - \mu) + \sum_k \|x_k - \mu\|^2$

$J = \min \Rightarrow \frac{\partial J}{\partial a_k} = 0 \Leftrightarrow a_k - e^T (x_k - \mu) = 0 \Rightarrow a_k = e^T (x_k - \mu)$

new data mean $(a_1, a_2, \dots, a_N) = E[\mu + a_k e] = \mu + E[a_k e] = \mu + e^T E[x_k - \mu]$
 $E[x_k - \mu] = 0$
 $= \mu$

implicit projections $x \rightarrow e$
 $= a$

$$J(e) = \sum_k a_k^2 - 2 \sum_k a_k e^T (x_k - \mu) + \sum_k \|x_k - \mu\|^2$$

$$= - \sum_k \underbrace{(e^T (x_k - \mu))^2}_{a_k^2} + \sum_k \|x_k - \mu\|^2$$

$$= - \sum_k e^T (x_k - \mu) (x_k - \mu)^T e + \sum_k \|x_k - \mu\|^2$$

covar matrix Σ

$$= -e^T \left[\sum_k (x_k - \mu)(x_k - \mu)^T \right] e$$

$$= -e^T \Sigma e$$

sigma

minimise $J(e)$

$$\min -e^T \Sigma e \quad \max e^T \Sigma e$$

max variance (projections)

Most important: what is the best e? want MAX

~~Var~~ Var [projections = new representations]

$$E[(\underbrace{\mu + a_{ve}}_{\text{proj}} - E[\mu + a_{ve}])^2] = E[(\mu + a_{ve} - \mu)^2] = E[(a_{ve})^2]$$

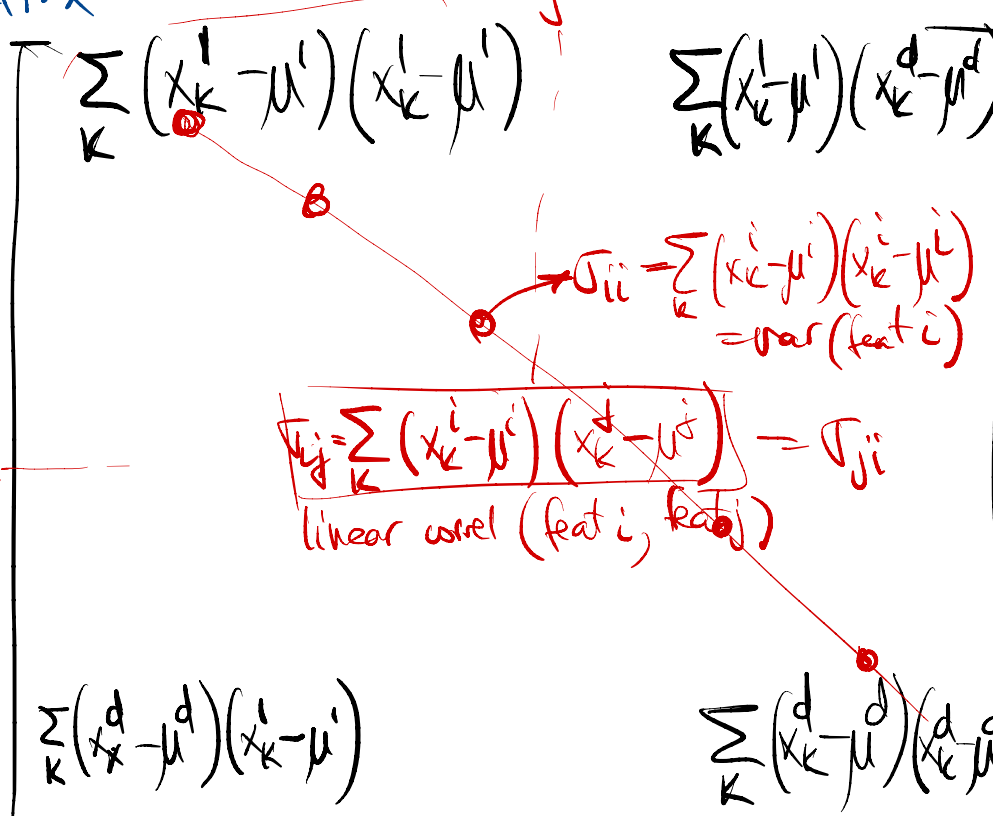
$$= E[e^T (x_k - \mu) \cdot e^T (x_k - \mu)] = E[e^T (x_k - \mu) (x_k - \mu)^T e]$$

sigma covar matrix

$$= e^T \sum_k e$$

$(1 \times d)$ $(d \times d)$ $(d \times 1)$ **MAX**

$$\sum_{\text{sigma}} = \sum_{\text{sum of matrices}} \underbrace{(x_k - \mu)}_{d \times 1} \underbrace{(x_k - \mu)^T}_{1 \times d}$$



Constrained optimization pb $\Sigma =$ ~~var~~ matrix = fixed

maximize $e^T \Sigma e$

subject to $\|e\|=1 \Leftrightarrow e^T e = 1$

Lagrangian

$L = \max \left[e^T \Sigma e - \alpha (e^T e - 1) \right]$

OR \downarrow Lag Multiplier \downarrow CONSTRAINED

$\frac{\partial L}{\partial e} = 0 \Leftrightarrow 2 \Sigma e = 2 \alpha e = 0$

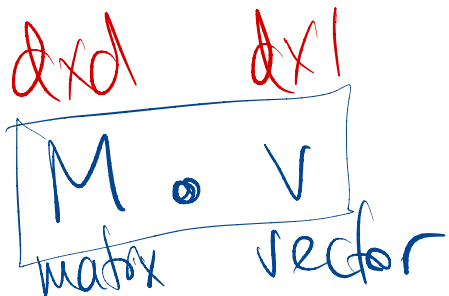
same direction as e

$\Sigma e = \alpha e$

sigma \downarrow scalar

$\|e\|$ does not change direction when $\|e\|$ multip by Σ !

usually changes direction of the vector.



$M \cdot v = \text{direction of } v \iff v - \text{eigen vector for } M$
 $M = \text{fixed}$
 λv
 \downarrow
scalar
 $\lambda = \text{eigen value}$

$$\Sigma = \text{covar}(X)$$

(1) symmetric

$$\Sigma_{ij} = \Sigma_{ji}$$

very
spectral

(2) pos def

$$v^T \Sigma v \geq 0$$

↓
allows spectral decomposition

e_i = eigen vectors of Σ
normalized

$$\Sigma = \begin{bmatrix} | & | & & | \\ e_1 & e_2 & \dots & e_d \\ | & | & & | \end{bmatrix} \begin{bmatrix} \alpha_1 & & & \\ & \alpha_2 & & \\ & & \dots & \\ & & & 0 \\ & & & & \dots & & \\ & & & & & & \alpha_d \end{bmatrix} \begin{bmatrix} \hline e_1 \\ \hline e_2 \\ \hline \vdots \\ \hline e_d \\ \hline \end{bmatrix}$$

eigenvec^T diag (eigen values) eigenvec

$$\alpha_1 \geq \alpha_2 \geq \dots \geq \alpha_d \geq 0$$

WANT t dim \Rightarrow take (top) t eigen values
make the rest 0