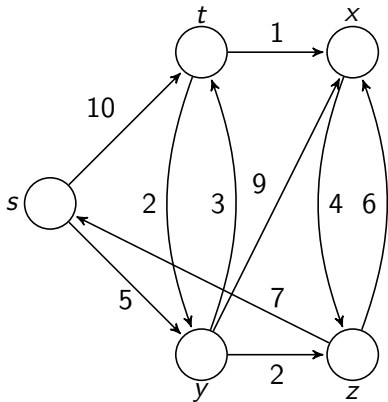
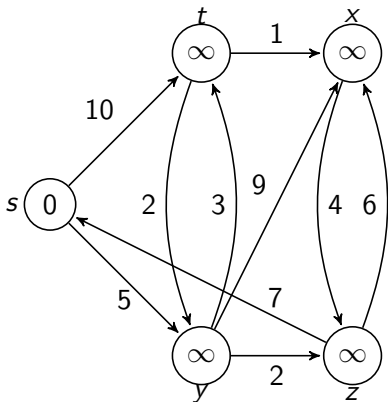


Dijkstra Algorithm

Cheng Li, Virgil Pavlu



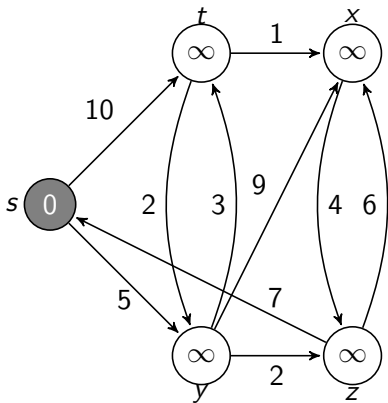
graph G
source = s



INITIALIZE -SINGLE
-SOURCE(G, s)

$S = \Phi$

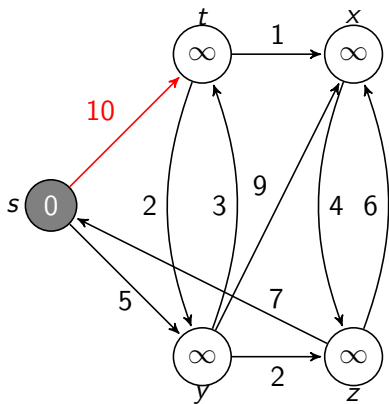
$Q = G.V$



$s = \text{EXTRACT-MIN}(Q)$

$S = \{s\}$

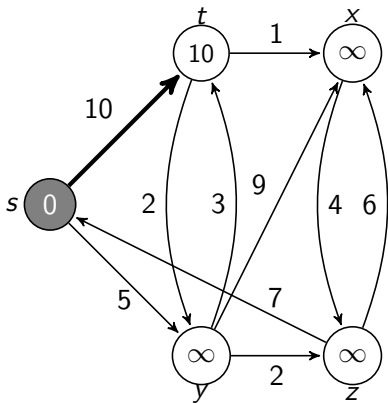
$Q = \{t, x, y, z\}$



RELAX(s, t, w)

$S = \{s\}$

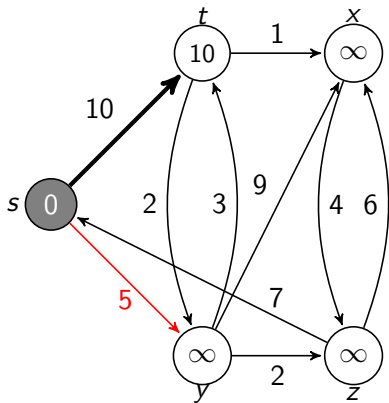
$Q = \{t, x, y, z\}$



RELAX(s, t, w)

$S = \{s\}$

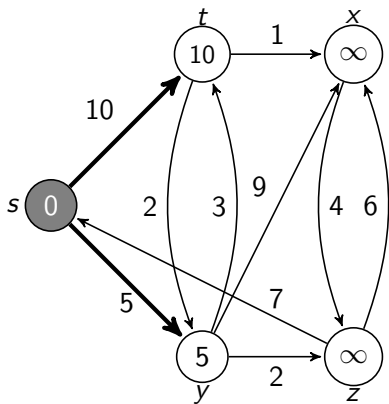
$Q = \{t, x, y, z\}$



RELAX(s, y, w)

$S = \{s\}$

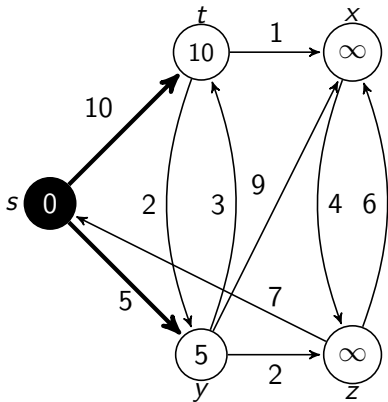
$Q = \{t, x, y, z\}$



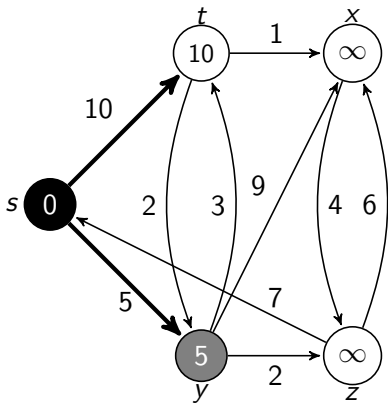
RELAX(s, y, w)

$S = \{s\}$

$Q = \{t, x, y, z\}$



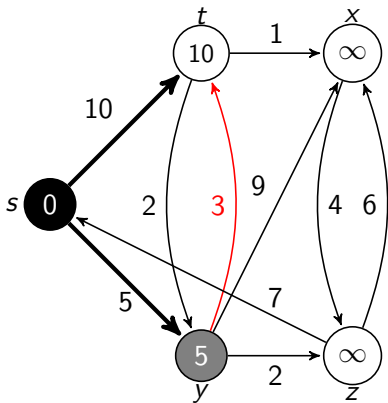
$S = \{s\}$
 $Q = \{t, x, y, z\}$



$y = \text{EXTRACT-MIN}(Q)$

$S = \{s, y\}$

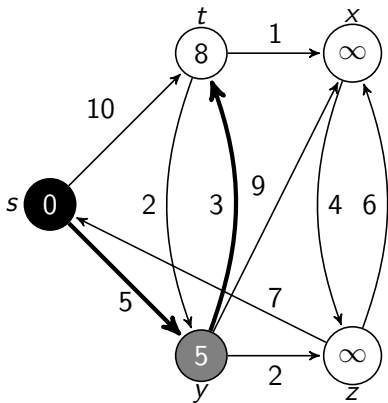
$Q = \{t, x, z\}$



RELAX(y, t, w)

$S = \{s, y\}$

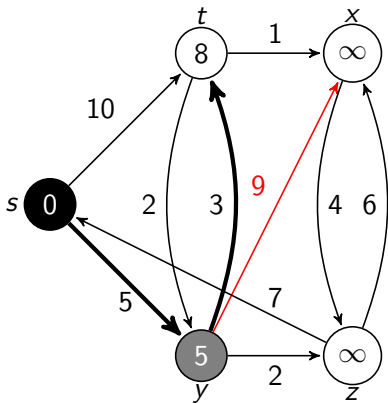
$Q = \{t, x, z\}$



RELAX(y, t, w)

$S = \{s, y\}$

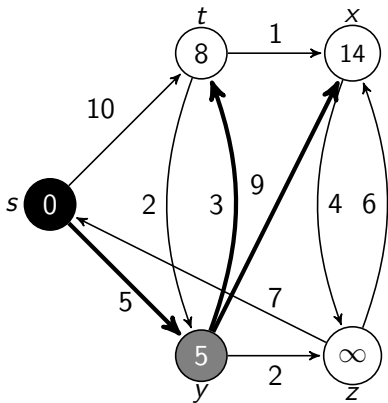
$Q = \{t, x, z\}$



RELAX(y, x, w)

$S = \{s, y\}$

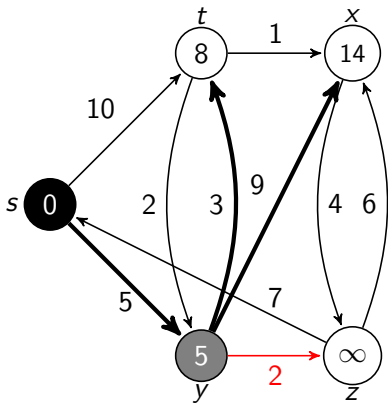
$Q = \{t, x, z\}$



RELAX(y, x, w)

$S = \{s, y\}$

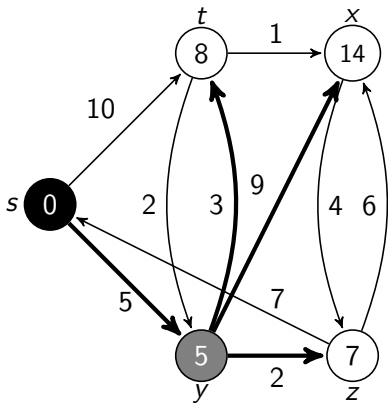
$Q = \{t, x, z\}$



RELAX(y, z, w)

$S = \{s, y\}$

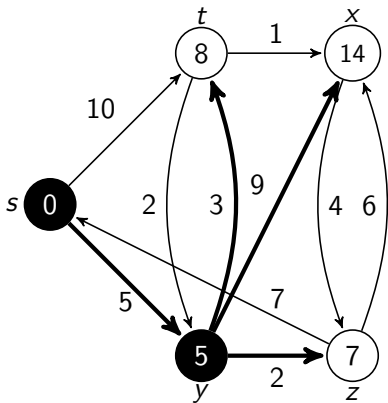
$Q = \{t, x, z\}$



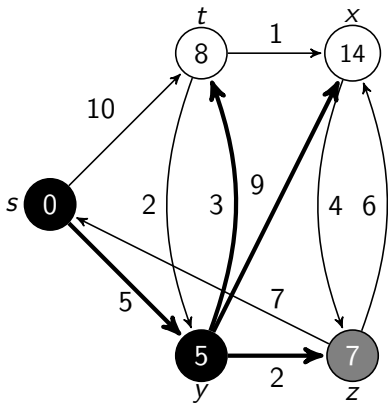
RELAX(y, z, w)

$S = \{s, y\}$

$Q = \{t, x, z\}$



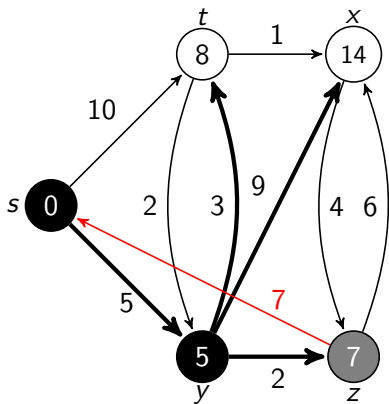
$S = \{s, y\}$
 $Q = \{t, x, z\}$



$z = \text{EXTRACT-MIN}(Q)$

$S = \{s, y, z\}$

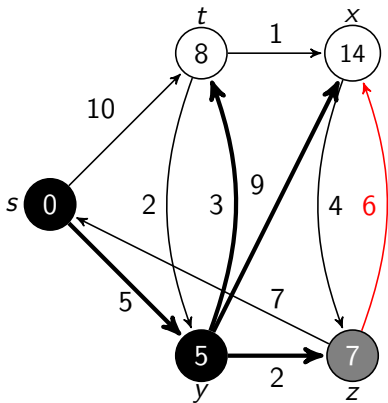
$Q = \{t, x\}$



$\text{RELAX}(z, s, w)$

$S = \{s, y, z\}$

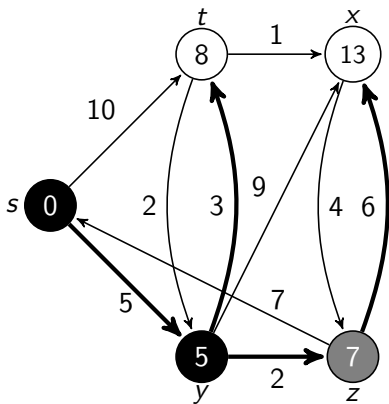
$Q = \{t, x\}$



$\text{RELAX}(z, x, w)$

$S = \{s, y, z\}$

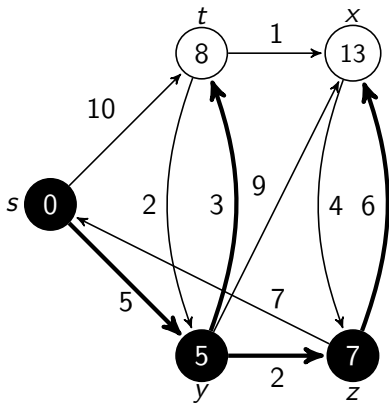
$Q = \{t, x\}$



$\text{RELAX}(z, x, w)$

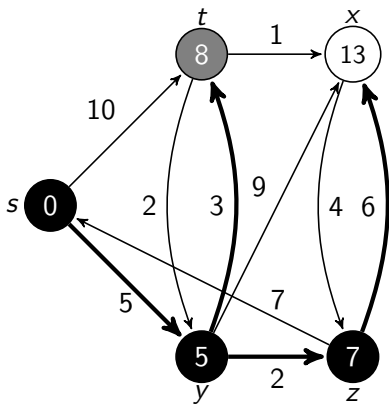
$S = \{s, y, z\}$

$Q = \{t, x\}$



$$S = \{s, y, z\}$$

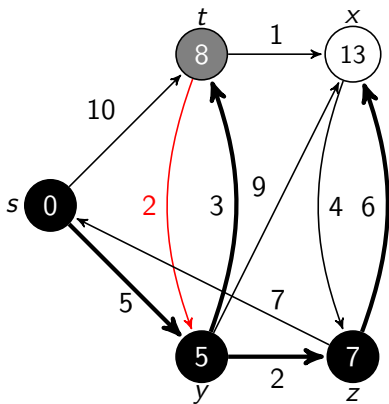
$$Q = \{t, x\}$$



$t = \text{EXTRACT-MIN}(Q)$

$S = \{s, y, z, t\}$

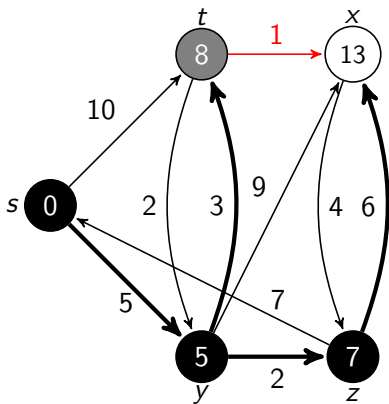
$Q = \{x\}$



$\text{RELAX}(t, y, w)$

$S = \{s, y, z, t\}$

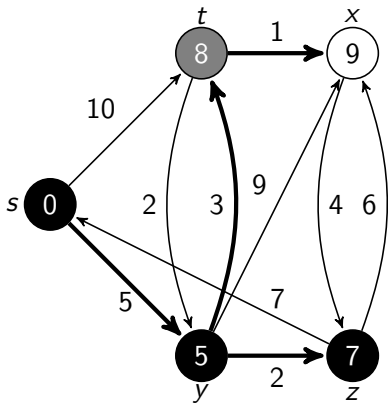
$Q = \{x\}$



$\text{RELAX}(t, x, w)$

$S = \{s, y, z, t\}$

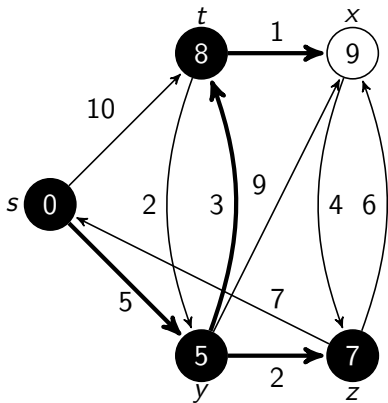
$Q = \{x\}$



$\text{RELAX}(t, x, w)$

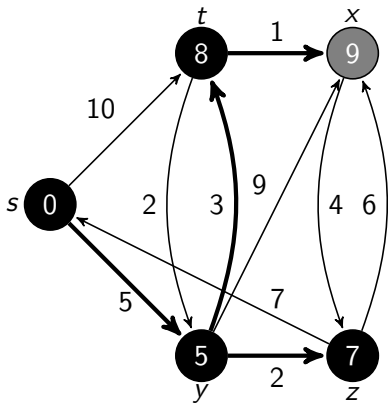
$S = \{s, y, z, t\}$

$Q = \{x\}$



$$S = \{s, y, z, t\}$$

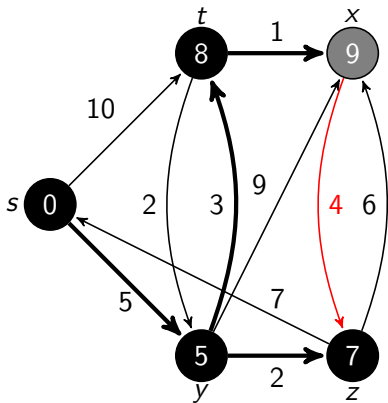
$$Q = \{x\}$$



$x = \text{EXTRACT-MIN}(Q)$

$S = G.V$

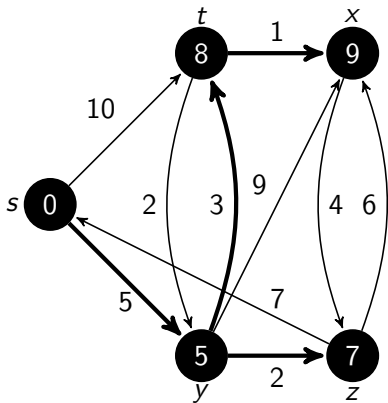
$Q = \Phi$



RELAX(x, z, w)

$S = G.V$

$Q = \Phi$



$S = G.V$

$Q = \Phi$

Done!