

CS 4830/7485

System Specification, Verification and Synthesis

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Program Synthesis

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PROGRAM SYNTHESIS

The “modern” approach to program synthesis

- Interactive:
 - computer-aided programming
 - programmer solves key problems (e.g., provides **program skeleton**), synthesizer fills in (boring or tedious) details (e.g., **missing guards/assignments**)
- Search-for-patterns based:
 - synthesis = search among set of user-defined patterns
- Solver based:
 - **heavily uses verifiers like SAT and SMT solvers**
 - often in a counter-example guided loop

Example: programming by sketching

[Solar-Lezama, Bodik, et al.]

Parallel Parking by Sketching

Ref: Chaudhuri, Solar-Lezama (PLDI 2010)

```
Err = 0.0;
for(t = 0; t < T; t += dT){
  if(stage == STRAIGHT){
    if(t > ??) stage = INTURN;
  }
  if(stage == INTURN){
    car.ang = car.ang - ??;
    if(t > ??) stage = OUTTURN;
  }
  if(stage == OUTTURN){
    car.ang = car.ang + ??;
    if(t > ??) break;
  }
  simulate_car(car);
  Err += check_collision(car);
}
Err += check_destination(car);
```

When to start turning?

Backup straight

Turn

Straighten

Enables programmers to focus on high-level solution strategy

Using SAT and SMT solvers for synthesis

Recall: what is synthesis?

$$\exists P: \forall x: \varphi(x, P(x))$$

Usually re-written as:

$$\exists P: \forall x: pre(x) \rightarrow post(x, P(x))$$

i.e., if input satisfies precondition, then output will satisfy postcondition.

Using SAT and SMT solvers for synthesis

$$\exists P: \forall x: pre(x) \rightarrow post(x, P(x))$$

Example of $pre()$, $post()$:

$$pre(x1, x2): number(x1) \wedge number(x2)$$

$$post(x1, x2, y): x1 \leq y \wedge x2 \leq y \wedge (x1 = y \vee x2 = y)$$

i.e., the spec for $\max(x1, x2)$.

First: using SAT and SMT solvers for verification

Suppose we already have a program P .

Then instead of checking whether P is **correct**

$$\forall x: pre(x) \rightarrow post(x, P(x))$$

we can check whether P is **wrong**

$$\exists x: pre(x) \wedge \neg post(x, P(x))$$

i.e., we can check **satisfiability** of the formula

$$pre(x) \wedge \neg post(x, P(x))$$

Hold on: are programs formulas?

Consider a simple loop-free program:

```
function P(int x) returns (real y)
{
  int tmp := 0;
  if (x >= 0) then {
    tmp++;
    y := tmp*x;
  }
  else
    y := -x;
  return y;
}
```

Formula:

$$P(x, y) = (x \geq 0 \wedge y = x) \vee (x < 0 \wedge y = -x)$$

Hold on: are programs formulas?

What about real programs?

Loops, data structures, libraries, pointers, threads, ...

Translation to formulas much harder, but verification tools are available that do this, constantly making progress.

We will assume we have a formula $P(x,y)$ representing the program P : *“ y is the output of P for input x ”*.

Back to using SAT and SMT solvers for verification

We can check **satisfiability** of the formula

$$pre(x) \wedge \neg post(x, P(x))$$

or, writing P as predicate on both input and output variables:

$$pre(x) \wedge P(x, y) \wedge \neg post(x, y)$$

Satisfiable \Rightarrow P is wrong: we get a **counter-example** (x,y)

Unsatisfiable \Rightarrow P is correct (for all x)

Using SAT and SMT solvers for synthesis

What can be done when we don't have the program P ?

$$pre(x) \wedge P(x, y) \wedge \neg post(x, y)$$

Hint: what if we have a finite/small number of candidate programs?

Iterate and search!

Programs with “holes”

Almost-complete programs:

```
Err = 0.0;
for(t = 0; t < T; t += dT){
  if(stage == STRAIGHT){
    if(t > ??) stage = INTURN;
  }
  if(stage == INTURN){
    car.ang = car.ang - ??;
    if(t > ??) stage = OUTTURN;
  }
  if(stage == OUTTURN){
    car.ang = car.ang + ??;
    if(t > ??) break;
  }
  simulate_car(car);
  Err += check_collision(car);
}
Err += check_destination(car);
```

When to start turning?

Backup straight

How much to turn?

Turn

Straighten



Programs with “holes”

What should we replace “??” with?

Patterns:

integer constants

linear expressions of the form $ax + by + c$ where x, y are variables in the program

...

Even with these restrictions, **infinite set of candidates** ...

Search may take a long time or never terminate.

Can we do better?

Asking the solver to find the program

Suppose our program has 1 hole, to be filled with an integer variable.

Then, the formula characterizing the program becomes

$$P(h, x, y)$$

Can we use the solver to find the right h ?

Check satisfiability of

Free variable: solver
must find right value

$$\forall x, y: pre(x) \wedge P(h, x, y) \rightarrow post(x, y)$$

Problem: universal quantification ...

$$\forall x, y: pre(x) \wedge P(h, x, y) \rightarrow post(x, y)$$

Today's solvers check satisfiability of quantifier-free formulas (mostly).

What can we do about that?

Hint: what if we have a finite number of **positive examples**? i.e., I/O pairs (x, y) satisfying $pre(x) \wedge post(x, y)$.

Example-guided synthesis

Suppose we have a finite number of positive examples,
say 2: $(x_1, y_1), (x_2, y_2)$.

That is: we know that these hold:

$$pre(x_1), pre(x_2), post(x_1, y_1), post(x_2, y_2)$$

So it suffices to check satisfiability of

$$P(h, x_1, y_1) \wedge P(h, x_2, y_2)$$

Example-guided synthesis

In general, for n positive examples and k hole variables:

$$\bigwedge_{i=1}^n P(h_1, h_2, \dots, h_k, x_i, y_i)$$

We turned universal quantification into finite conjunction!

Example-guided synthesis

What if solver finds this formula unsatisfiable ?

$$\bigwedge_{i=1}^n P(h_1, h_2, \dots, h_k, x_i, y_i)$$

Unsatisfiable => no program exists!

This is **sound**: if no program exists that works even in this finite set of examples, we cannot hope to find a program that works for all examples.

Example-guided synthesis

What if solver finds this formula satisfiable ?

$$\bigwedge_{i=1}^n P(h_1, h_2, \dots, h_k, x_i, y_i)$$

Satisfiable $\Rightarrow P(h_1, h_2, \dots, h_k)$ is only a candidate.

It still needs to be verified for **all** I/O pairs.

We can again use the solver for that!

Example-guided synthesis

$$\bigwedge_{i=1}^n P(h_1, h_2, \dots, h_k, x_i, y_i)$$

Satisfiable $\Rightarrow P(h_1, h_2, \dots, h_k)$ is only a candidate.

Verify it by checking satisfiability of

$$pre(x) \wedge \underbrace{P(h_1, h_2, \dots, h_k, x, y)}_{\text{These are now fixed}} \wedge \neg post(x, y)$$

If formula is unsatisfiable then we are done!

What if formula is satisfiable?

Our candidate is wrong. We get a counter-example:

What then?

$$(x^*, y^*)$$

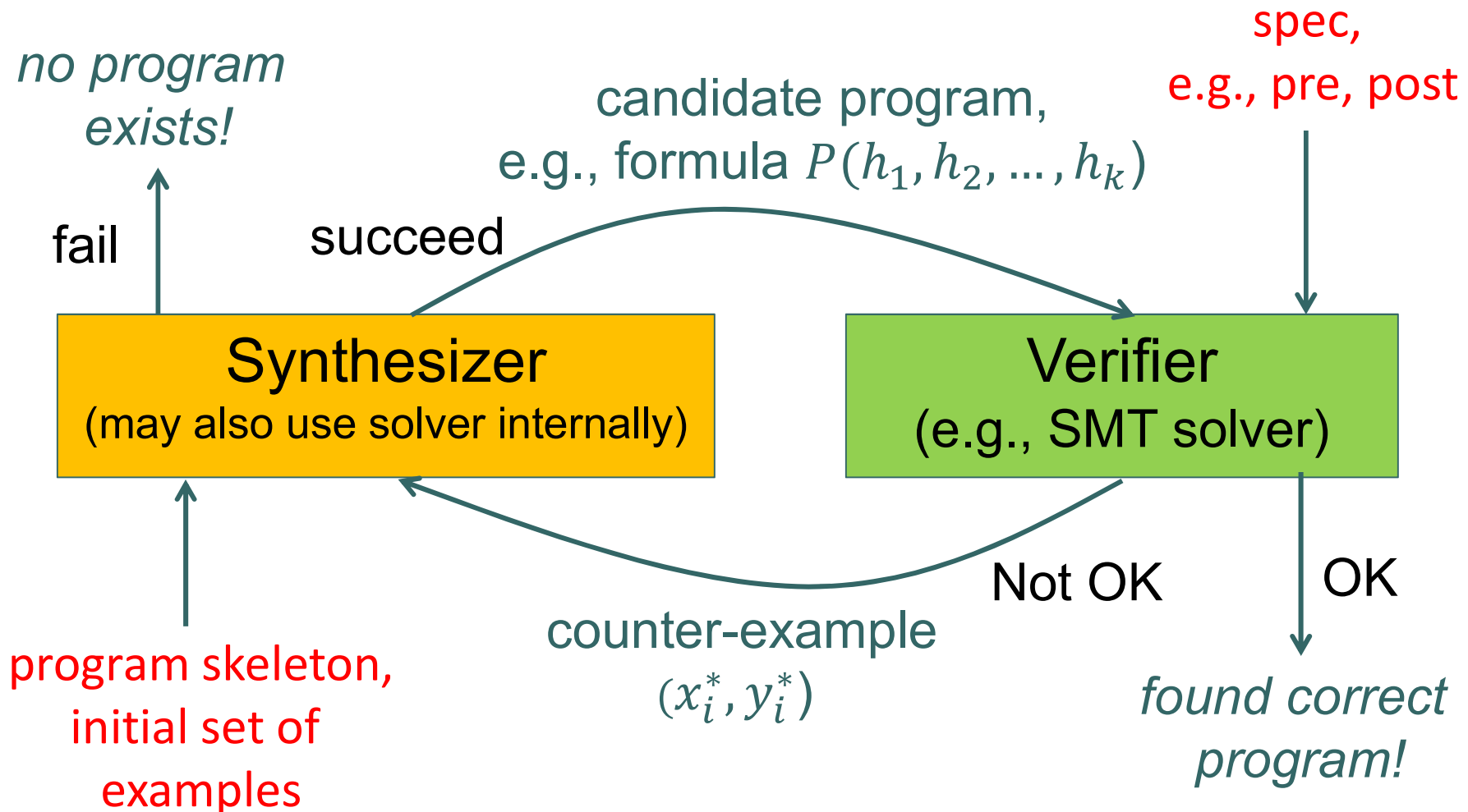
Adding negative examples to the synthesizer's inputs

In general, for n positive examples, m negative examples, and k hole variables:

$$\bigwedge_{i=1}^n P(h_1, h_2, \dots, h_k, x_i, y_i) \wedge \bigwedge_{i=1}^m \neg P(h_1, h_2, \dots, h_k, x_i^*, y_i^*)$$

Alternative: the user could provide the correct output for the counter-example input, or we could use a reference (correct and deterministic) program.

Counter-example guided synthesis



References

1. Solar-Lezama. *Program sketching*. STTT Vol 15, Issue 5-6, Oct 2013.
2. Alur, Bodik, et al. *Syntax-Guided Synthesis*. FMCAD 2013.
3. International Journal on Software Tools for Technology Transfer, Special Issue on Synthesis, Volume 15, Issue 5-6, October 2013.
4. Course by Ras Bodik and Emina Torlak. CS294 – *Program Synthesis for Everyone*. <https://homes.cs.washington.edu/~bodik/ucb/cs294fa12.html>